

# Introduction to Time & Frequency

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# Outline

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- 1) What is time ?
- 2) How to measure it ?
- 3) How to characterize such measurement :  
Noise, Instability and Accuracy
- 4) How to make a common time reference and dispatch it ?
- 5) Risks/cybersecurity

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# What is time ?

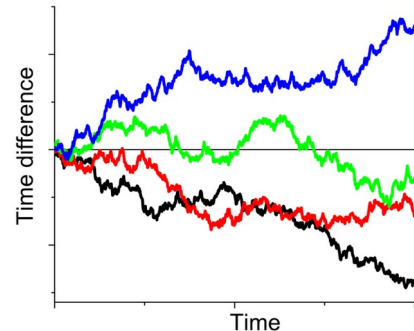
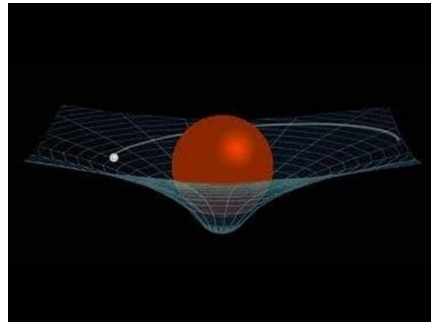


“What, then, is time?  
If no one asks me, I know;  
if I wish to explain to him who asks, I know not”  
St Augustine (Confessions XI, ~400AD)

Common sense = Newtonian time = universal coordinate of events  
(Note : different from Aristotle & Leibnitz point of view → maybe not so “natural”)

Modern Physics: not so simple ! (relativity, quantum mechanics, etc...)

→ only “proper time” is truly meaningful ; “universality” requires some  
~arbitrary collective decisions



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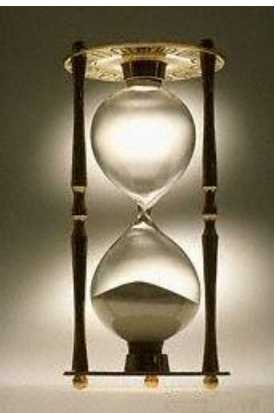
# How to measure (proper) time

Needs something that changes in a regular and predictable/reproducible manner

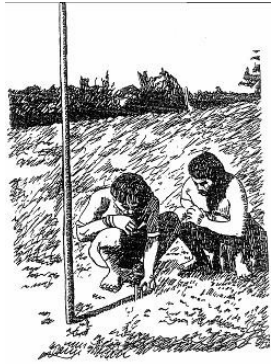
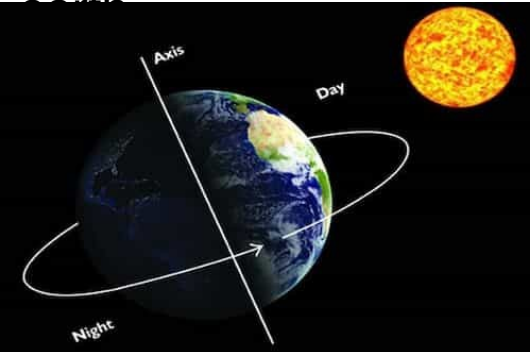
Water clock



Hour glass



A "universal" good candidate: rotation of the earth

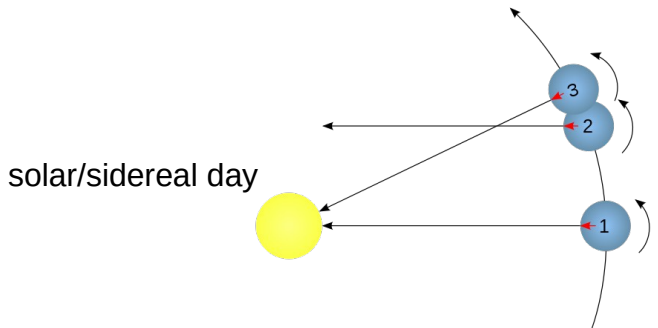


$$t = K \times \theta_{\text{earth}}$$

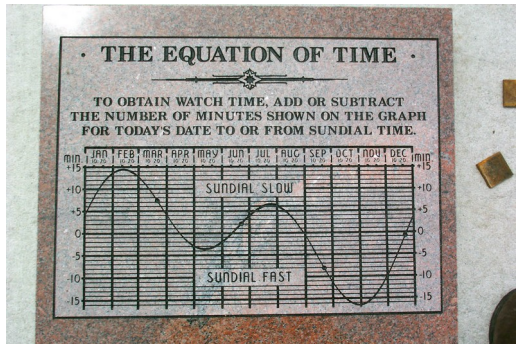
Gnomons, sundials, meridian telescopes

# Rotation of the earth as timekeeping

Until 1956, SI unit of time (s) defined as : 1/86400 of the mean solar day

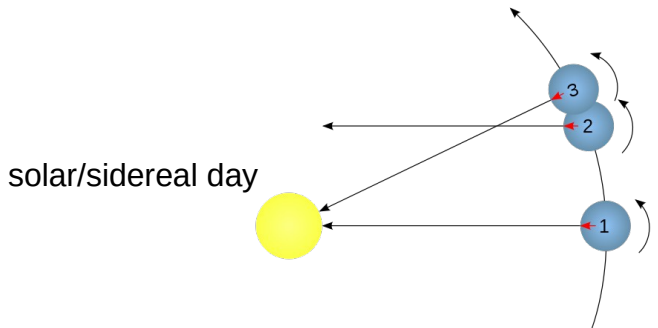


Equation of time

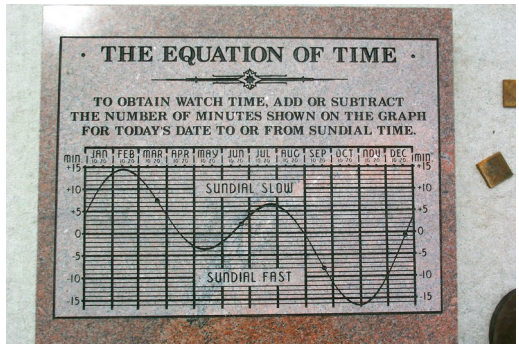


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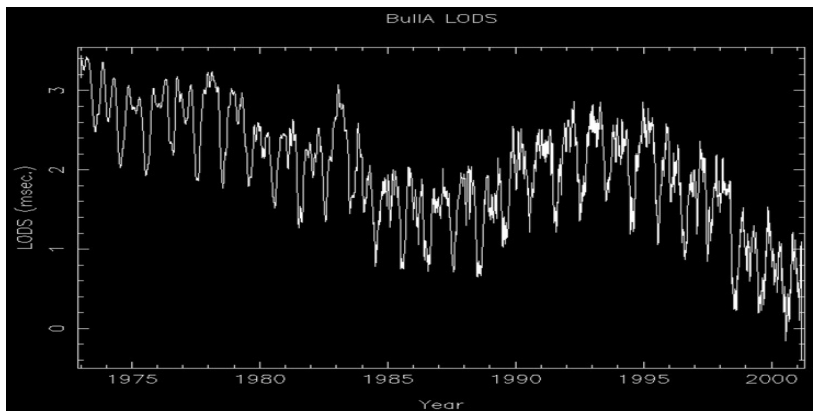


Equation of time



But it seriously fluctuates !

- tides (moon, sun)
- inner effects (core-mantle interface)
- atmosphere/meteorology effects
- hydrology
- seismic effects (earthquakes, tsunnamis)
- ...

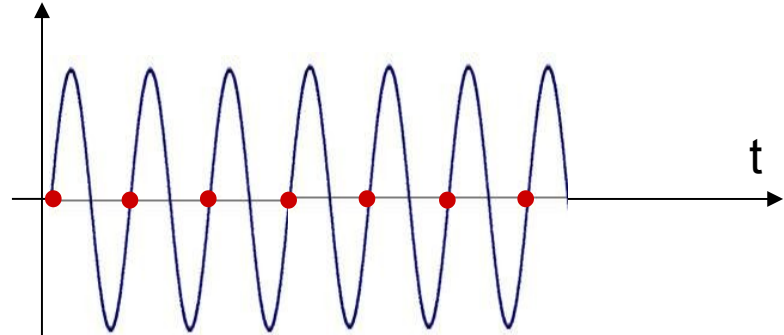


1956 to 1967 : the fraction 1/31,556,925.9747 of the tropical year 1900  
1 tropical year = 365,2422 solar days = 366,2422 sidereal days



# Man-made oscillators/frequency standards

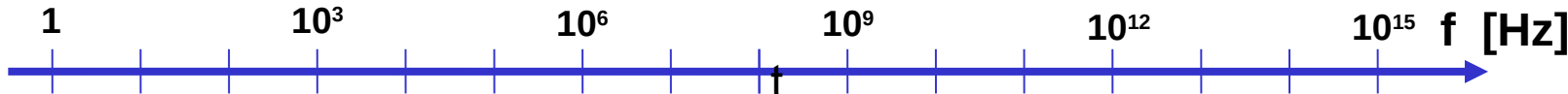
Physical signal



$$s(t) = A \cos(2\pi\nu_0 t) = A \cos [\Phi(t)]$$

$$t = \frac{\Phi}{2\pi\nu_0}$$

(generally update t measured in a discrete manner – typically each time  $\phi = 2n\pi$ )



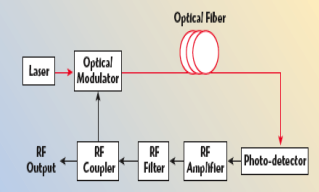
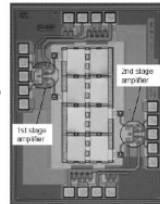
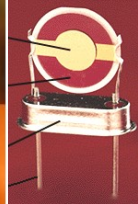
Oscillator →

mechanical

quartz  
(+ MEMS)

microwave

laser



+ atomic transition between energy levels reference

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# The noisy oscillator

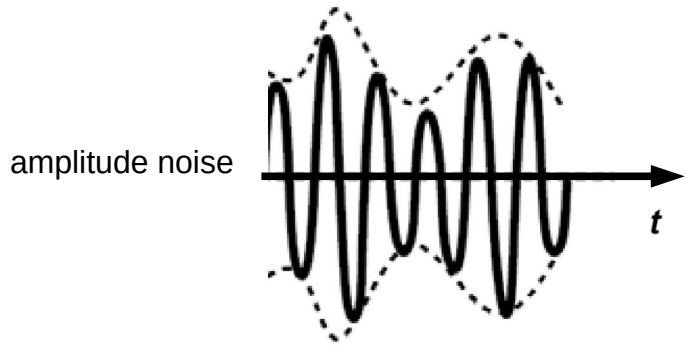
Real Oscillator :

$$\begin{cases} s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(1 + y(t))t + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu t + \phi(t) + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(t + x(t)) + \phi_0] \end{cases}$$

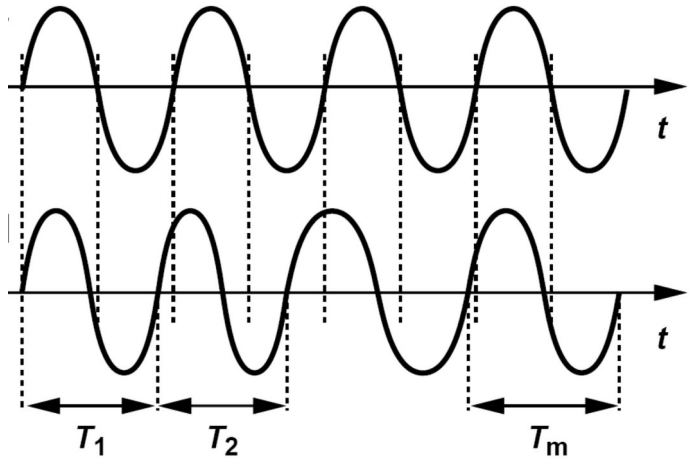
Different descriptions of the same signal...

Different descriptions of the same effect...

- $\alpha(t)$  : amplitude noise
- $y(t)$  : relative frequency noise
- $\phi(t)$  : phase noise
- $x(t)$  : timing noise



frequency/phase/timing noise



# Time measurement, Noise and Divergence

Real Oscillator :

$$\begin{cases} s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(1 + y(t))t + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu t + \delta\phi(t) + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(t + x(t)) + \phi_0] \end{cases}$$

$\alpha(t)$  : amplitude noise  
(physically bounded)

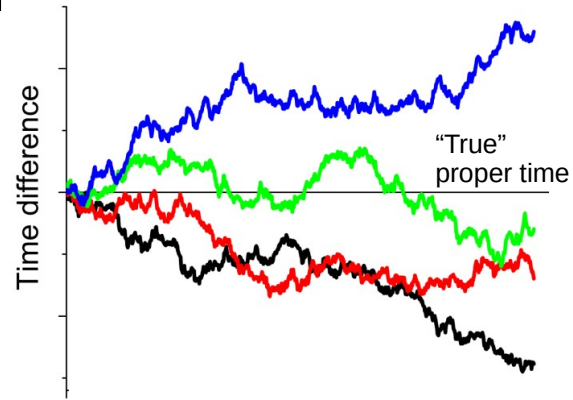
$y(t)$  : relative frequency noise  
(physically bounded)

Different descriptions  
of the same effect...

$\phi(t)$  : phase noise  
**(not physically bounded, always divergent !)**

$x(t)$  : timing noise  
**(not physically bounded, always divergent !)**

Different descriptions  
of the same signal...



Two **real** (un-coupled) clocks, as **identical** as can be, measuring **the same proper time** will **always diverge** after a while unless you apply some feed-back/coupling mechanism

# Mathematical tools for random signals

Real Oscillator : 
$$\begin{cases} s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(1 + y(t))t + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu t + \phi(t) + \phi_0] \\ s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu(t + x(t)) + \phi_0] \end{cases}$$

Different descriptions of the same signal...

Most utilized statistical tools in TF, for a random variable  $v$  (unit [u]):

- **power spectral density**  $S_v(f)$  (unit  $u^2/Hz$ , often  $dB(u^2/Hz)$ ), sometimes  $\sqrt{S_v(f)}$  (unit  $u/\sqrt{Hz}$ )

$S_\alpha(f) S_y(f) S_\phi(f) S_x(f) \text{ etc.}$

→ ~ rms fluctuations measured in a BW of 1Hz around a Fourier frequency  $f$  (mostly used for “short” <1s timescales)

- **2-sample variances/deviations (ADEV, TDEV,...):**

Un-normalized ADEV (can use it also for random variables other than frequency...)

$\sigma_y(\tau)$   $\sigma_{\nu y}(\tau)$  [Hz]  $\sigma_x(\tau)$  [s]

ADEV of y

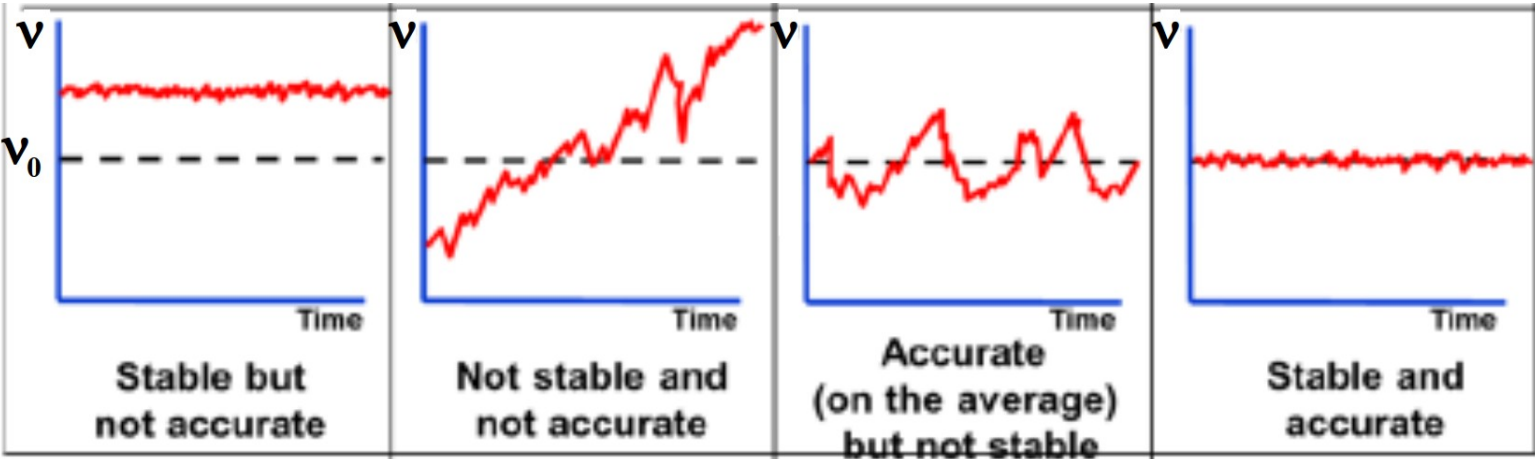
→ ~ “typical” fluctuations between consecutive measurements of duration  $\tau$  (mostly used for “long” >1s timescales)

# Instability and accuracy

Real frequency standard at  $\nu_0$ :  $s(t) = A_0[1 + \alpha(t)] \cos[2\pi\nu_0(1 + \epsilon + y(t))t + \phi_0]$

Instability: quantifies the frequency fluctuations at a given time scale  $\tau$   
mathematical tools: 2-sample variance (AVAR) and family, extracted from  $y(t)$   
decreases (more or less) with increasing  $\tau$

Systematic error/bias  $\epsilon$ : how wrong you believe you can be from the target frequency  
You can only estimate it (and maybe you forgot something important)!  
(note: low instability often helps such estimation experimentally)



(From J. Vig tutorial)

# Instability and accuracy

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Note : “precision” is rarely used appropriately, and most people only have a vague understanding of what it means  $\Rightarrow$  mostly stay away from it !

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# Problems of clocks and timekeeping

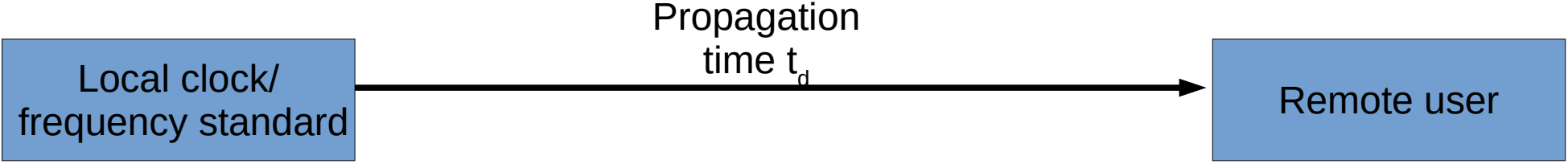
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- 1) Clocks only measure their proper time, not an “absolute” time (which doesn’t exist...)
  - ➔ comparing (good) clocks require compensation of relativistic effects (gravitational shift, relative speed)... level of knowledge of the correction ?
- 2) Multiple clocks – even when measuring the same proper time – will always diverge (in an unpredictable way)
  - ➔ Every clock in the world needs some kind of feed-back to stay (more or less) in agreement with the others (how often = “holdover”)

Solution:

- clocks comparisons
- International collaboration (BIPM) and timescale steering (EAL, TAI, UTC(k), UTC )

# Frequency and Time dissemination

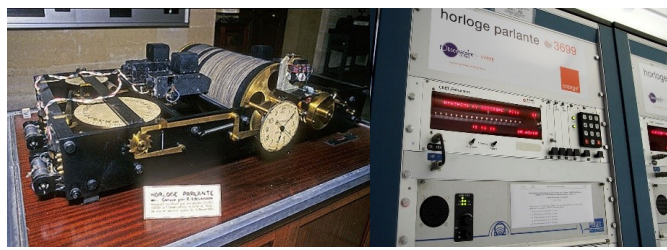


$t_d$  constant: desynchronisation

$t_d$  fluctuates: desynchronisation + desyntonisation (frequency detuning)

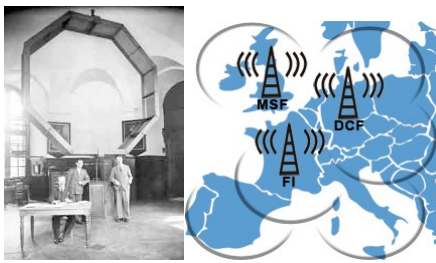
a priori knowledge of  $t_d$  allows (up to a point) correction

Talking clock

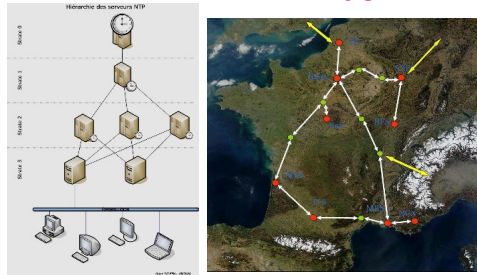


Yann Le Coq

Longwave transmission (DCF77, ALS162, ...)

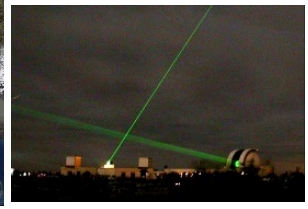


Telecom (NTP, WR) Fiber

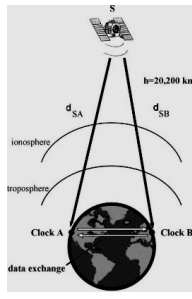


Introduction to T&F

Laser links

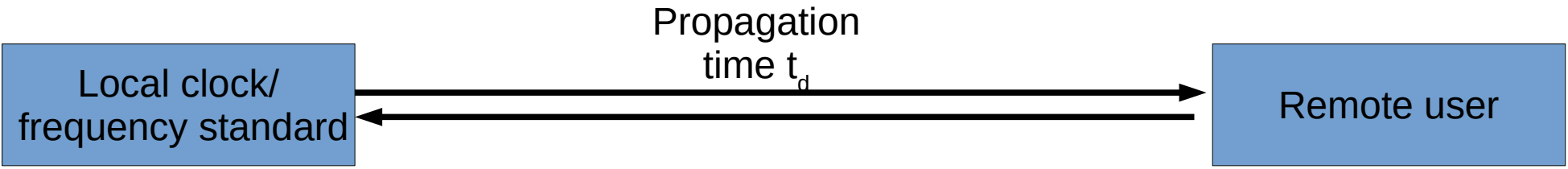


GNSS TWSTFT



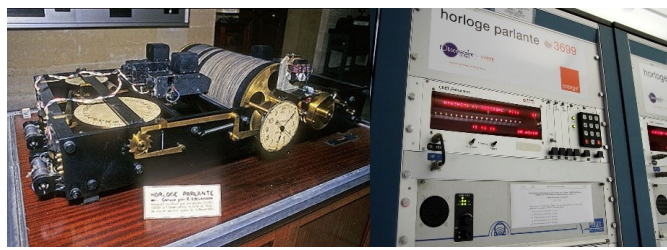
13th of November 2024

# Frequency and Time dissemination



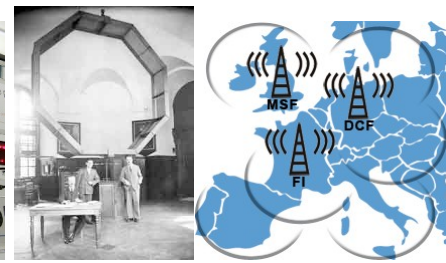
Two-way transfer: allows measuring  $t_d$ , and correcting for it

Talking clock

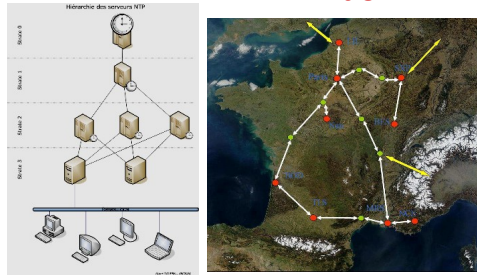


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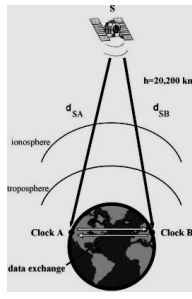


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GNSS  
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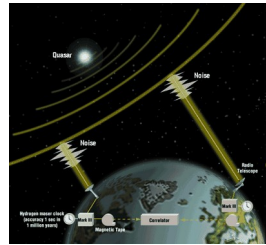
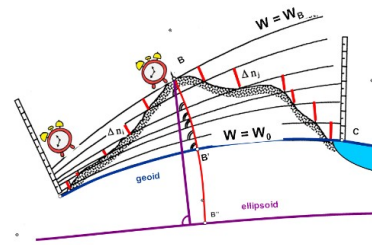
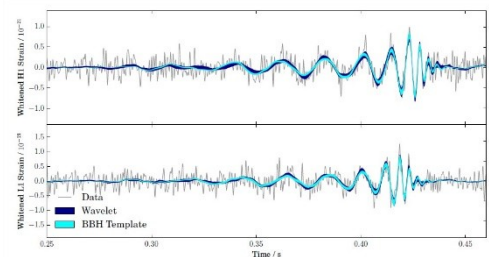
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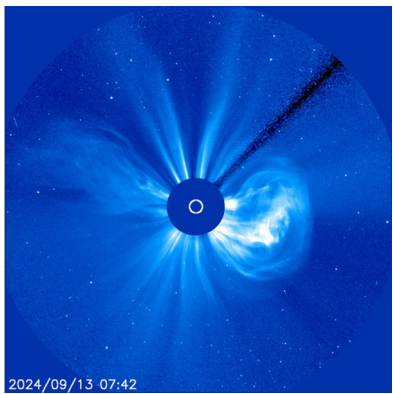
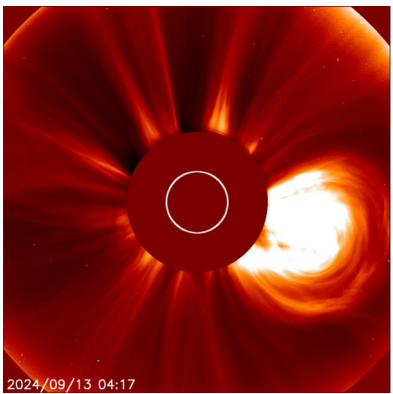
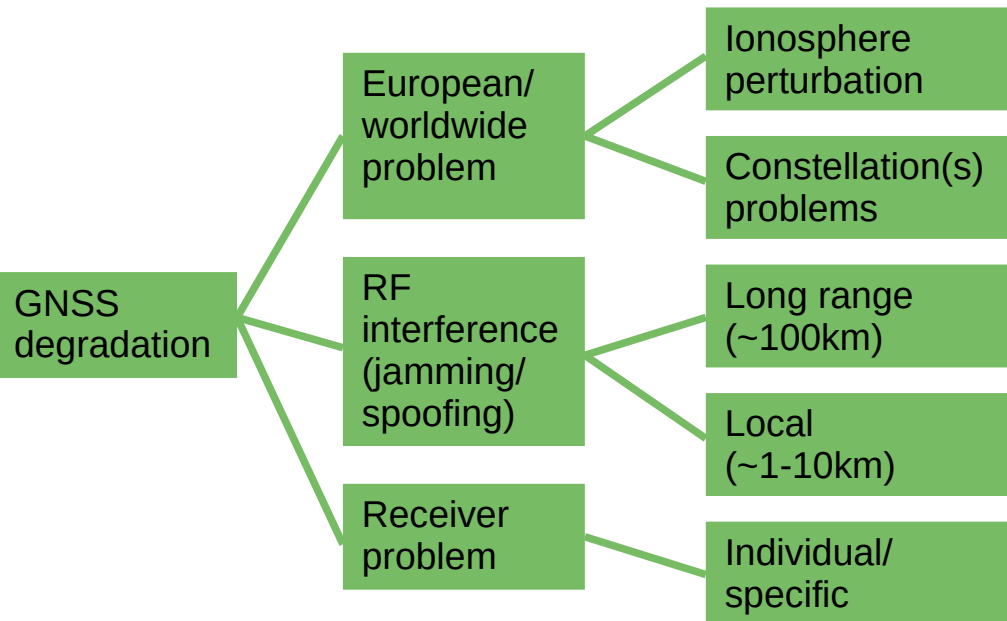
# Time references and distribution networks are everywhere...

- Fundamental metrology (SI units),
- Fundamental physics (drift of fundamental constants, gravitational shift, ...)
- Detection of gravitation waves, relativistic chronometric geodesy
- Astronomy (pulsars time tagging)
  
- Local oscillators in any electronic devices, PLL, filters, sensors
- Ranging, positioning, navigation, GNSS
- Network synchronisation: telecom, datacenter, smart grids, DSN, VLBI, SKA
- RADAR, LIDAR, atmosphere analysis, ...
  
- Banks (MIFID 2), justice, police, hospitals, etc. → requirements for traceability

...



# Risks associated with GNSS (and others...)



## Cyber-security objectives

- Availability
- Integrity/authenticity
- Traceability
- Confidentiality

